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Candidate surname					Other names					
Centre Number				Candidate Number				<b>SAMPLE SOLUTIONS</b>		
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<b>Pearson Edexcel Level 3 GCE</b>										
<b>Tuesday 20 June 2023</b>										
Afternoon					Paper reference		<b>9MA0/32</b>			
<b>Mathematics</b>										
<b>Advanced</b>										
<b>PAPER 32: Mechanics</b>										
<b>You must have:</b> Mathematical Formulae and Statistical Tables (Green), calculator								Total Marks		

**Candidates may use any calculator allowed by Pearson regulations. Calculators must not have the facility for symbolic algebra manipulation, differentiation and integration, or have retrievable mathematical formulae stored in them.**

### Instructions

- Use **black** ink or ball-point pen.
- If pencil is used for diagrams/sketches/graphs it must be dark (HB or B).
- **Fill in the boxes** at the top of this page with your name, centre number and candidate number.
- Answer **all** questions and ensure that your answers to parts of questions are clearly labelled.
- Answer the questions in the spaces provided  
– *there may be more space than you need.*
- You should show sufficient working to make your methods clear. Answers without working may not gain full credit.
- Unless otherwise indicated, whenever a value of  $g$  is required, take  $g = 9.8 \text{ m s}^{-2}$  and give your answer to either 2 significant figures or 3 significant figures.

### Information

- A booklet 'Mathematical Formulae and Statistical Tables' is provided.
- The total mark for this part of the examination is 50. There are 6 questions.
- The marks for **each** question are shown in brackets  
– *use this as a guide as to how much time to spend on each question.*

### Advice

- Read each question carefully before you start to answer it.
- Try to answer every question.
- Check your answers if you have time at the end.

Turn over ►

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1. A car is initially at rest on a straight horizontal road.

The car then accelerates along the road with a constant acceleration of  $3.2 \text{ ms}^{-2}$

Find

- (a) the speed of the car after 5 s, (1)
- (b) the distance travelled by the car in the first 5 s. (2)

a) Because acceleration is constant so you can use SUVAT equations

$$v = u + at$$

↪ initially at rest  $\therefore u = 0 \text{ ms}^{-1}$

$$\begin{aligned} v &= 0 + (3.2)(5) \\ &= 16 \text{ ms}^{-1} \end{aligned}$$

$$\text{b) } s = ut + \frac{1}{2}at^2$$

↑  $u = 0$

$$\begin{aligned} s &= 0 + \frac{1}{2}(3.2)(5)^2 \\ &= 40 \text{ m} \end{aligned}$$



2.



Figure 1

A particle  $P$  has mass 5 kg.

The particle is pulled along a rough horizontal plane by a horizontal force of magnitude 28 N.

The only resistance to motion is a frictional force of magnitude  $F$  newtons, as shown in Figure 1.

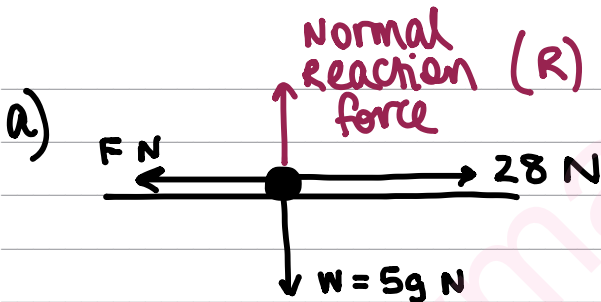
- (a) Find the magnitude of the normal reaction of the plane on  $P$  (1)

The particle is accelerating along the plane at  $1.4 \text{ ms}^{-2}$

- (b) Find the value of  $F$  (2)

The coefficient of friction between  $P$  and the plane is  $\mu$

- (c) Find the value of  $\mu$ , giving your answer to 2 significant figures. (1)



because the particle isn't accelerating in the vertical direction ( $\updownarrow$ ), the forces must be resolved in the vertical

(i.e. resultant vertical force = 0)

$$\begin{aligned} \therefore R &= W \\ R &= 5g = 5 \times 9.8 \\ &= 49 \text{ N} \end{aligned}$$



Question 2 continued

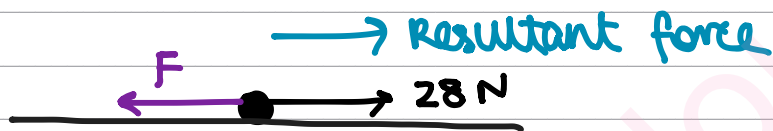
b) because particle has frictional force to left, friction opposes motion,  $\therefore$  particle is moving to the right

$\therefore$  resultant force is to the right

$$\text{resultant force} \rightarrow F = m a \leftarrow \text{acceleration}$$

↖ mass

$$F = 5 \times 1.4 = 7 \text{ N}$$



$$28 - F = \text{resultant force} = 7 \text{ N}$$

$$\therefore F = 28 - 7 = 21 \text{ N}$$

c) friction force (F) =  $\mu R$

↖ coefficient of friction

↑ normal reaction force

$$21 = \mu \times 49$$

$$\mu = \frac{3}{7} = 0.4286 \dots$$

$$\therefore \mu = 0.43 \quad (2 \text{ s.f.})$$

(Total for Question 2 is 4 marks)



3. At time  $t$  seconds, where  $t \geq 0$ , a particle  $P$  has velocity  $v \text{ ms}^{-1}$  where

$$\mathbf{v} = (t^2 - 3t + 7)\mathbf{i} + (2t^2 - 3)\mathbf{j}$$

Find

- (a) the speed of  $P$  at time  $t = 0$  (3)
- (b) the value of  $t$  when  $P$  is moving parallel to  $(\mathbf{i} + \mathbf{j})$  (2)
- (c) the acceleration of  $P$  at time  $t$  seconds (2)
- (d) the value of  $t$  when the direction of the acceleration of  $P$  is perpendicular to  $\mathbf{i}$  (2)

$$a) \quad \mathbf{v} = \begin{pmatrix} t^2 - 3t + 7 \\ 2t^2 - 3 \end{pmatrix}$$

$$\text{when } t=0 \quad \mathbf{v} = \begin{pmatrix} 0 - 0 + 7 \\ 0 - 3 \end{pmatrix} = \begin{pmatrix} 7 \\ -3 \end{pmatrix}$$

speed is the magnitude of velocity

$$\text{speed} = \sqrt{7^2 + (-3)^2} = \sqrt{49 + 9} = \sqrt{58} \text{ ms}^{-1}$$

don't forget J units

b) when  $P$  is moving parallel to  $(\mathbf{i} + \mathbf{j})$ ,

it means that the velocity is parallel to the vector (i.e. motion)  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\mathbf{v} = \begin{pmatrix} t^2 - 3t + 7 \\ 2t^2 - 3 \end{pmatrix} \uparrow\uparrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

parallel means that the vectors are multiples of each other



Question 3 continued

$$\therefore k \begin{pmatrix} t^2 - 3t + 7 \\ 2t^2 - 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$k(t^2 - 3t + 7) = 1 = k(2t^2 - 3)$$

$$t^2 - 3t + 7 = 2t^2 - 3$$

$$t^2 + 3t - 10 = 0$$

$$(t + 5)(t - 2) = 0 \quad \leftarrow \text{factorise}$$

$$t = -5 \cup 2 \text{ s}$$

$\uparrow$  but  $t$  cannot be negative

$$\therefore t = 2 \text{ s}$$

c) acceleration is the derivative of velocity

$$v = \begin{pmatrix} t^2 - 3t + 7 \\ 2t^2 - 3 \end{pmatrix} \quad a = \frac{d}{dt}(v) = v'$$

$$v' = a = \begin{pmatrix} 2t - 3 \\ 4t \end{pmatrix} \quad a = (2t - 3)i + (4t)j$$

$\uparrow$  same format as qu.

d) when acceleration is perpendicular to  $i$ ,  
parallel to  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$



$$k \begin{pmatrix} 2t - 3 \\ 4t \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad k(2t - 3) = 0 \quad k(4t) = 1$$

$$\therefore 2t - 3 = 0 \quad \text{but } k \neq 0$$

$$t = \frac{3}{2} \text{ s}$$

(Total for Question 3 is 9 marks)



4. [In this question,  $\mathbf{i}$  and  $\mathbf{j}$  are horizontal unit vectors and position vectors are given relative to a fixed origin  $O$ ]

A particle  $P$  is moving on a smooth horizontal plane.

The particle has constant acceleration  $(2.4\mathbf{i} + \mathbf{j})\text{ms}^{-2}$

At time  $t = 0$ ,  $P$  passes through the point  $A$ .

At time  $t = 5$  s,  $P$  passes through the point  $B$ .

The velocity of  $P$  as it passes through  $A$  is  $(-16\mathbf{i} - 3\mathbf{j})\text{ms}^{-1}$

- (a) Find the speed of  $P$  as it passes through  $B$ .

(4)

The position vector of  $A$  is  $(44\mathbf{i} - 10\mathbf{j})\text{m}$ .

At time  $t = T$  seconds, where  $T > 5$ ,  $P$  passes through the point  $C$ .

The position vector of  $C$  is  $(4\mathbf{i} + c\mathbf{j})\text{m}$ .

- (b) Find the value of  $T$ .

(3)

- (c) Find the value of  $c$ .

(3)

2) velocity is the integral of acceleration

$$v = \int a \, dt$$

$$a = \begin{pmatrix} 2.4 \\ 1 \end{pmatrix} \quad v = \begin{pmatrix} 2.4t + c \\ t + d \end{pmatrix}$$

when passes P:

$$t = 0$$

$$v = \begin{pmatrix} -16 \\ -3 \end{pmatrix} = v = \begin{pmatrix} 2.4(0) + c \\ (0) + d \end{pmatrix}$$

↑ different constants of integration

$$\begin{pmatrix} -16 \\ -3 \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix}$$

$$\therefore v = \begin{pmatrix} 2.4t - 16 \\ t - 3 \end{pmatrix}$$



Question 4 continued

when passes B:  $t = 5$ 

$$v = \begin{pmatrix} 2 \cdot 4(5) - 16 \\ (5) - 3 \end{pmatrix} = \begin{pmatrix} 12 - 16 \\ 5 - 3 \end{pmatrix} = \begin{pmatrix} -4 \\ 2 \end{pmatrix}$$

speed is magnitude of velocity

$$\text{speed} = \sqrt{(-4)^2 + 2^2} = \sqrt{16 + 4} = \sqrt{20} = 2\sqrt{5} \text{ ms}^{-1}$$

$\swarrow \sqrt{4 \times 5} = \sqrt{2^2 \times 5}$

b) METHOD 1: (integrate velocity)

displacement is the integral of velocity

displacement  $\rightarrow s = \int v \, dt$ 

$$v = \begin{pmatrix} 2 \cdot 4t - 16 \\ t - 3 \end{pmatrix} \quad s = \int \begin{pmatrix} 2 \cdot 4t - 16 \\ t - 3 \end{pmatrix} dt$$

$$= \begin{pmatrix} 1.2t^2 - 16t + a \\ 0.5t^2 - 3t + b \end{pmatrix}$$

at A:  $t = 0$ 

$$s = \begin{pmatrix} 44 \\ -10 \end{pmatrix}$$

$$s = \begin{pmatrix} 44 \\ -10 \end{pmatrix} = \begin{pmatrix} 1.2(0)^2 - 16(0) + a \\ 0.5(0)^2 - 3(0) + b \end{pmatrix}$$

$$\begin{pmatrix} 44 \\ -10 \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} \quad \therefore s = \begin{pmatrix} 1.2t^2 - 16t + 44 \\ 0.5t^2 - 3t - 10 \end{pmatrix}$$



Question 4 continued

METHOD 2: (use SUVAT vector equations)

$$s = \bar{v}_A t + \frac{1}{2} \bar{a} t^2 + \bar{s}_A$$

$$s = \begin{pmatrix} -16 \\ -3 \end{pmatrix} t + \frac{t^2}{2} \begin{pmatrix} 2.4 \\ 1 \end{pmatrix} + \begin{pmatrix} 44 \\ -10 \end{pmatrix}$$

$$s = \begin{pmatrix} 1.2t^2 - 16t + 44 \\ 0.5t^2 - 3t - 10 \end{pmatrix}$$

when  $t = T$ , passes through C

$$s = \begin{pmatrix} 4 \\ c \end{pmatrix} = \begin{pmatrix} 1.2T^2 - 16T + 44 \\ 0.5T^2 - 3T - 10 \end{pmatrix}$$

$$1.2T^2 - 16T + 40 = 0 \quad \leftarrow \text{quadratic solver}$$

$$T = 10 \quad \vee \quad \frac{10}{3} \quad \text{but } T > 5$$

$$\therefore T = 10 \text{ s}$$

$$c) \quad c = 0.5(10)^2 - 3(10) - 10$$

$$= 0.5(100) - 30 - 10$$

$$= 50 - 40$$

$$= 10$$

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5.

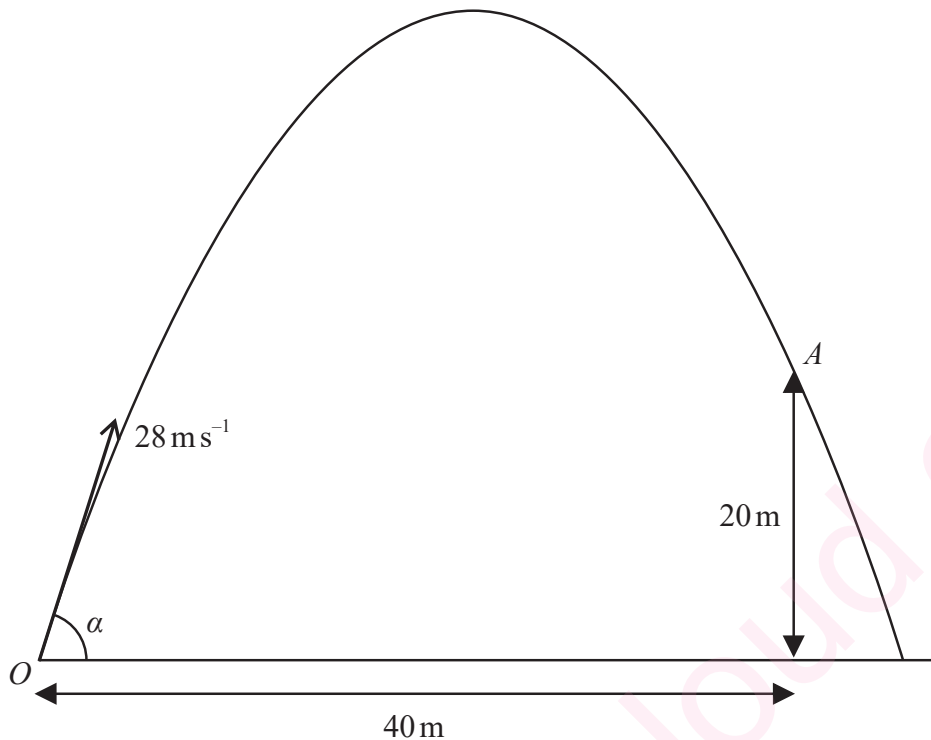


Figure 2

A small ball is projected with speed  $28 \text{ m s}^{-1}$  from a point  $O$  on horizontal ground.

After moving for  $T$  seconds, the ball passes through the point  $A$ .

The point  $A$  is  $40 \text{ m}$  horizontally and  $20 \text{ m}$  vertically from the point  $O$ , as shown in Figure 2.

The motion of the ball from  $O$  to  $A$  is modelled as that of a particle moving freely under gravity.

Given that the ball is projected at an angle  $\alpha$  to the ground, use the model to

(a) show that  $T = \frac{10}{7 \cos \alpha}$  (2)

(b) show that  $\tan^2 \alpha - 4 \tan \alpha + 3 = 0$  (5)

(c) find the greatest possible height, in metres, of the ball above the ground as the ball moves from  $O$  to  $A$ . (3)

The model does not include air resistance.

(d) State one other limitation of the model. (1)

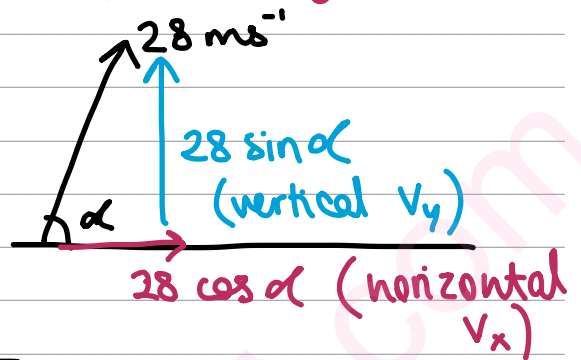


Question 5 continued

a) Horizontal velocity is constant (assuming no air resistance)

time =  $\frac{\text{distance}}{\text{speed}}$

time at  
↓ A  
 $T = \frac{\text{horizontal distance to A}}{\text{horizontal component velocity}}$



$$T = \frac{40}{28 \cos \alpha} = \frac{10}{7 \cos \alpha}$$

b) In the vertical direction, there is only 1 force (gravity), acting downwards, so there is constant acceleration & can use SUVAT equations

$$s = ut + \frac{1}{2}at^2$$

(taking upwards direction to be positive)

$$20 = (28 \sin \alpha)T - \frac{g}{2}T^2$$

(gravity acts down, so negative)

$$T = \frac{10}{7 \cos \alpha} \quad \downarrow \quad 20 = \frac{28 \sin \alpha \times 10}{7 \cos \alpha} - \frac{g}{2} \left( \frac{10}{7 \cos \alpha} \right)^2$$

$$20 = 40 \tan \alpha - \frac{9.8 \times 100}{2 \times 49 \cos^2 \alpha}$$

$$20 = 40 \tan \alpha - 10 \sec^2 \alpha$$

$$2 = 4 \tan \alpha - \sec^2 \alpha$$



Question 5 continued

$$\cos^2 \theta + \sin^2 \theta = 1 \quad (\div \text{ by } \cos^2 \theta)$$

$$1 + \frac{\sin^2 \theta}{\cos^2 \theta} = \frac{1}{\cos^2 \theta}$$

$$1 + \tan^2 \theta = \sec^2 \theta$$

$$2 = 4 \tan \alpha - \sec^2 \alpha$$

← replace by identity

$$2 = 4 \tan \alpha - (1 + \tan^2 \alpha)$$

$$3 = 4 \tan \alpha - \tan^2 \alpha$$

$$\tan^2 \alpha - 4 \tan \alpha + 3 = 0$$

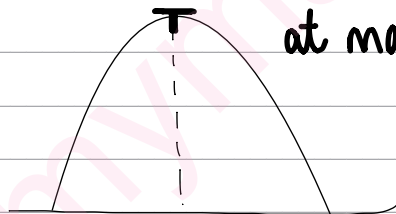
c) solve quadratic equation with  $\tan \alpha$   
 $\tan \alpha = m$

$$m^2 - 4m + 3 = 0$$

$$(m-3)(m-1) = 0$$

$$m = \tan \alpha = 1 \cup 3$$

Max height :

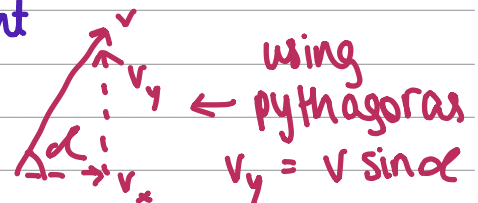
at max height :  $v_y = 0$ ↑  
vertical component  
of velocitySUVAT :  $v^2 = u^2 + 2as$ 

$$v^2 = 0 = (v_{y(\text{original})})^2 + 2as$$

← max height displacement

$$0 = (v \sin \alpha)^2 - 2gs$$

$$s = \frac{v^2 \sin^2 \alpha}{2g}$$

using  
pythagoras  
 $v_y = v \sin \alpha$ 

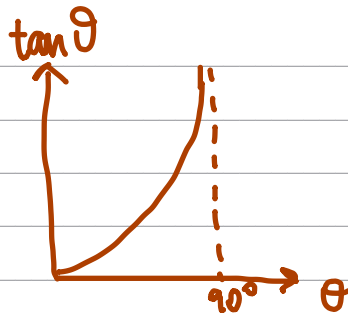
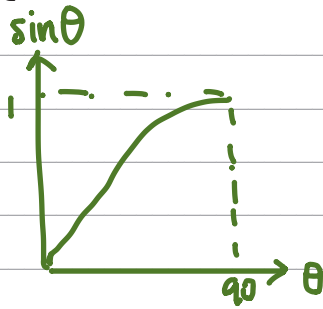
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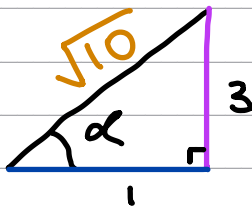
Question 5 continued



The bigger the value of  $\tan \theta$   
the bigger the value of  $\sin \theta$

$\therefore$  for the highest value of  $\sin \theta$ , choose the largest value of  $\tan \theta$

$$\tan \alpha = 1 \vee 3 \quad \therefore \text{larger value: } \tan \alpha = 3$$



$$\tan \alpha = \frac{\text{opposite}}{\text{adjacent}} = 3$$

using pythagoras, hypotenuse =  $\sqrt{3^2 + 1^2} = \sqrt{10}$

$$\sin \alpha = \frac{\text{opposite}}{\text{hypotenuse}} = \frac{3}{\sqrt{10}}$$

$$\text{max height} = \frac{v^2 \sin^2 \alpha}{2g} = \frac{28^2 \times \left(\frac{3}{\sqrt{10}}\right)^2}{2 \times 9.8}$$

$$= \frac{784 \times 9}{2 \times 9.8 \times 10} = 36 \text{ m}$$

d)  $\rightarrow$  dimensions of ball (not a particle)

$\rightarrow$  there could be wind, affecting the ball's velocity  
(not in freefall with only gravity acting)

(Total for Question 5 is 11 marks)



6.

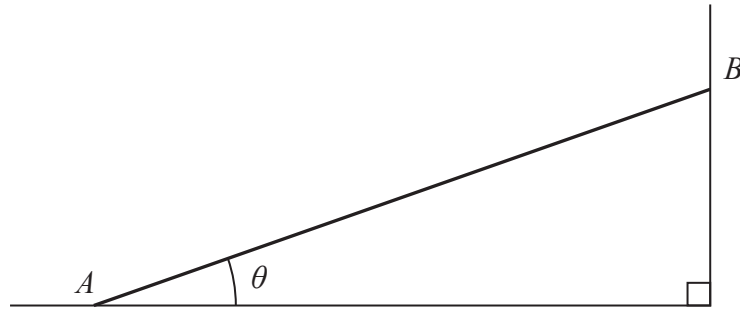


Figure 3

A rod  $AB$  has mass  $M$  and length  $2a$ .

The rod has its end  $A$  on rough horizontal ground and its end  $B$  against a smooth vertical wall.

The rod makes an angle  $\theta$  with the ground, as shown in Figure 3.

The rod is at rest in limiting equilibrium.

- (a) State the direction (left or right on Figure 3 above) of the frictional force acting on the rod at  $A$ . **Give a reason for your answer.**

(1)

The magnitude of the normal reaction of the wall on the rod at  $B$  is  $S$ .

In an initial model, the rod is modelled as being **uniform**.

**Use this initial model to answer parts (b), (c) and (d).**

- (b) By taking moments about  $A$ , show that

$$S = \frac{1}{2} Mg \cot \theta$$

(3)

The coefficient of friction between the rod and the ground is  $\mu$

Given that  $\tan \theta = \frac{3}{4}$

- (c) find the value of  $\mu$

(5)

- (d) find, in terms of  $M$  and  $g$ , the magnitude of the resultant force acting on the rod at  $A$ .

(3)

In a new model, the rod is modelled as being **non-uniform**, with its centre of mass closer to  $B$  than it is to  $A$ .

A new value for  $S$  is calculated using this new model, with  $\tan \theta = \frac{3}{4}$

- (e) State whether this new value for  $S$  is larger, smaller or equal to the value that  $S$  would take using the initial model. **Give a reason for your answer.**

(1)

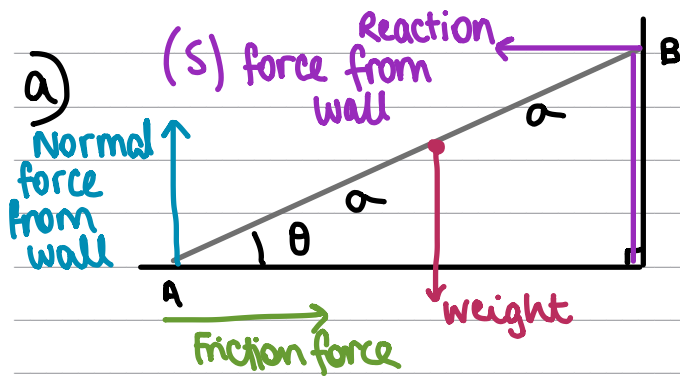
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Question 6 continued



For ruler to be in equilibrium, both vertical & horizontal forces must be balanced

The weight balances the normal force from the wall

The reaction force from the wall to the left must be balanced by a friction force to the right

b) Taking moments about A:

Anticlockwise moment:  $S \times$  perpendicular distance from force to pivot

$$S \times 2a \sin \theta$$

Clockwise moment:  $W \times$  perpendicular distance from force to pivot

$$W \times a \cos \theta$$

For the ruler to be in equilibrium:

anticlockwise moment = clockwise moment

$$S \times 2a \sin \theta = W \times a \cos \theta$$

$$S = \frac{W \times a \cos \theta}{2a \sin \theta} = \frac{Mg}{2 \tan \theta} = \frac{1}{2} Mg \cot \theta$$

Question 6 continued

$$c) \text{ Friction force} = \text{Normal contact force from wall} \times \mu$$

coefficient of friction

$$\text{Normal contact force from wall} = \text{weight} \quad \left( \begin{array}{l} \text{resolve forces} \\ \text{vertically} \end{array} \right)$$

$$\text{Friction force} = S$$

$$\mu M g = \frac{1}{2} M g \cot \theta$$

$$\mu = \frac{M g \cot \theta}{2 \times M g} \quad \leftarrow \begin{array}{l} \tan \theta = \frac{3}{4} \\ \cot \theta = \frac{4}{3} \end{array}$$

$$\mu = \frac{1}{2} \times \frac{4}{3} = \frac{2}{3}$$

d) magnitude of resultant force at A

$$= \sqrt{(\text{normal})^2 + F^2}$$

$$\sqrt{(Mg)^2 + \left(\frac{2}{3}Mg\right)^2}$$

$$= \sqrt{\frac{13}{9} (Mg)^2}$$

$$= \frac{\sqrt{13} Mg}{3}$$

e) If the centre of mass is closer B, then the clockwise moment would be bigger. This means that the anticlockwise moment must be bigger, so S must also be larger.

